



# Dictionary Learning for Spontaneous Neural Activity Modeling

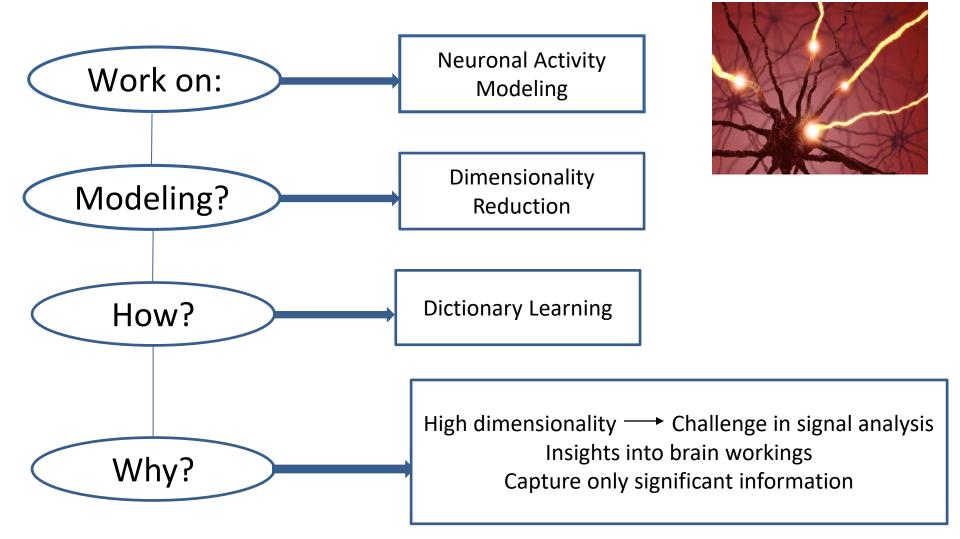
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- I. Introduction
- II. Proposed Approach
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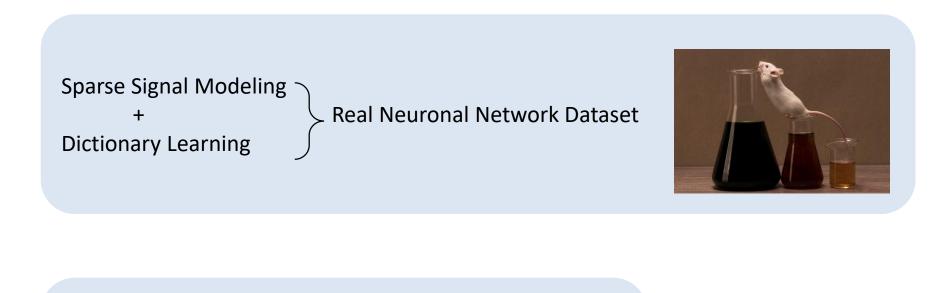
## What - Why - How

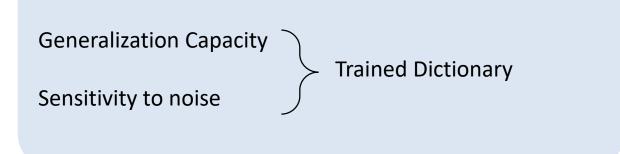


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#### Introduction

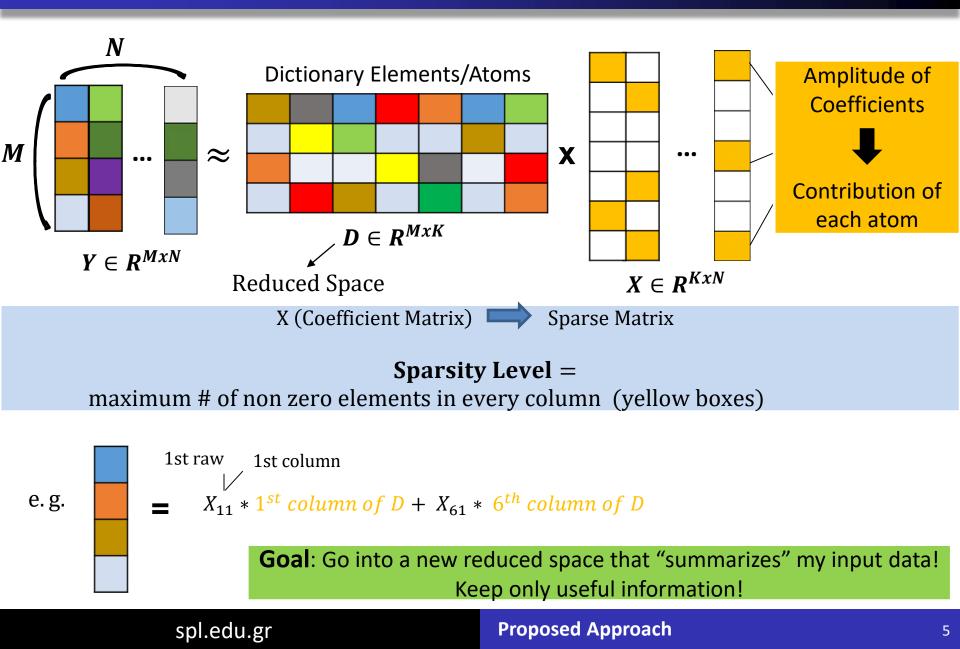
### **Innovative Aspects**





#### Introduction

# **Sparse Signal Modeling**



# Why Imposing the Criterion of Sparsity?



- 1. Time Complexity
- 2. Avoid Overfitting

# **More General Examples**

- > If **Y** was an image, dictionary should capture:
- Important Edges
- Intensities



- > If **Y** was a song, dictionary should capture:
- Basic notes and their combinations



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## Norms

### Norms:

*zero norm*: 
$$||x||_0 = (i|x_i \neq 0)$$

$$l_1 norm: ||x||_1 = \sum_{i=1}^R |x|_i$$

$$l_2 norm: ||x||_2 = (\sum_{i=1}^R |x|_i^2)^{1/2}$$

$$l_p norm: ||x||_p = (\sum_{i=1}^R |x|_i^p)^{1/p}$$

Frobenius norm (matrix norm): 
$$||x||_F =$$

$$\left|\sum_{i=1}^{M}\sum_{j=1}^{N}\left|x_{ij}\right|^{2}\right|$$

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# **Orthogonal Matching Pursuit (OMP)**

### **Optimization Problem – Sparse Coding:**

 $\min_{x_i} \|\boldsymbol{y}_i - \boldsymbol{D}\boldsymbol{x}_i\|_2^2 \quad subject \ to \quad \|\boldsymbol{x}_i\|_0 \le T_0 \ \forall i, \qquad where$ 

 $y_i$ : input vector D: trained dictionary  $x_i$ : coefficient vector  $\|.\|_0$  : zero norm  $T_0$ : Sparsity Level

#### **OMP** (Orthogonal Matching Pursuit)

**Basic Idea:** Approximately represent a signal y as a weighted sum of finitely many functions  $d_i$  (dictionary elements) taken from D. For an approximation with N dictionary elements:

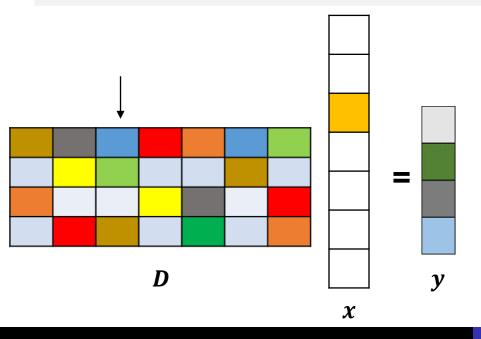
$$y = \sum_{j=1}^{N} x_j d_j$$
 , where

 $x_i$  is the scalar weighting factor (coefficient) for  $d_i$ 

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# **OMP** Visualization

- 1. Set the residual  $r_1 = y$ Iteratively: Set j=1
- 2. Find an unselected atom that best matches the residual  $||r^j Dx||$
- 3. Get the coefficient of *x*
- 4. Recalculate the residual from matched atoms  $r^{j+1} = r^j Dx$
- 5. Repeat until  $||r^j|| \leq \epsilon$



$$r_1 = y$$
  
 $r_2 = r_1 - x_j d_j = y - x_j d_j$   
 $r_3 = r_2 - x_{j'} d_{j'} = y - x_j d_j - x_{j'} d_{j'}$ 

$$r_n = y - \sum_{j=1}^N x_j d_j$$

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# **Dictionary Learning**

The Dictionary can be one of the following:

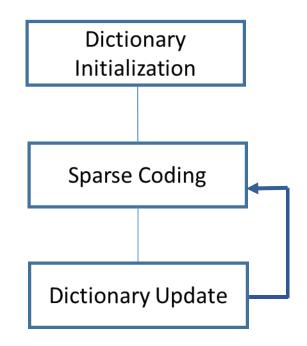
- Parametric: Fourier signals, wavelets, etc.
- <u>Trained</u>: Learning from randomly selected input examples

### **K-SVD Algorithm**

For Sparsity Level  $T_0$ , K-SVD solves the following:

$$\min_{D,X} ||Y - DX||_F^2 \text{ subject to } ||X_i||_0 \leq T_0 \quad \forall i, \text{ where}$$

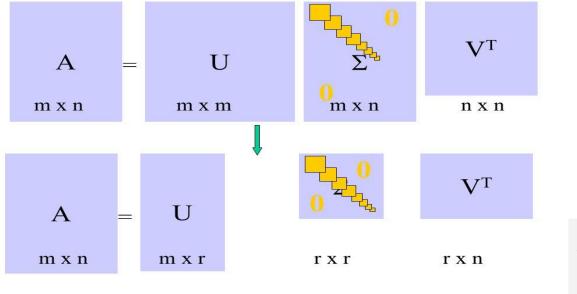
Y: Input Signal D: Trained Dictionary X: Coefficient Matrix  $\|.\|_F$  denotes the Frobenius norm  $T_0$ : sparsity level



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# **Singular Value Decomposition (SVD)**





A singular value and a pair of singular vectors of a matrix A are a nonnegative scalar σ and two nonzero vectors u and v s.t.:

 $Au = \sigma v$   $A^{H}v = \sigma u$   $A^{H}$  denotes the complex conjugate transpose of a matrix

U is an mxm orthogonal matrix

Σ is a diagonal mxn matrix with non-negative real numbers in the diagonal (singular values of A)

V is an nxn orthogonal matrix

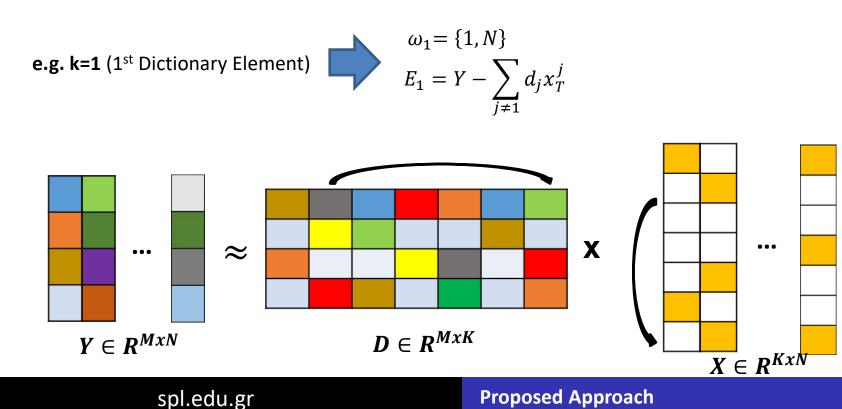
 $V^T$  is the transpose of V

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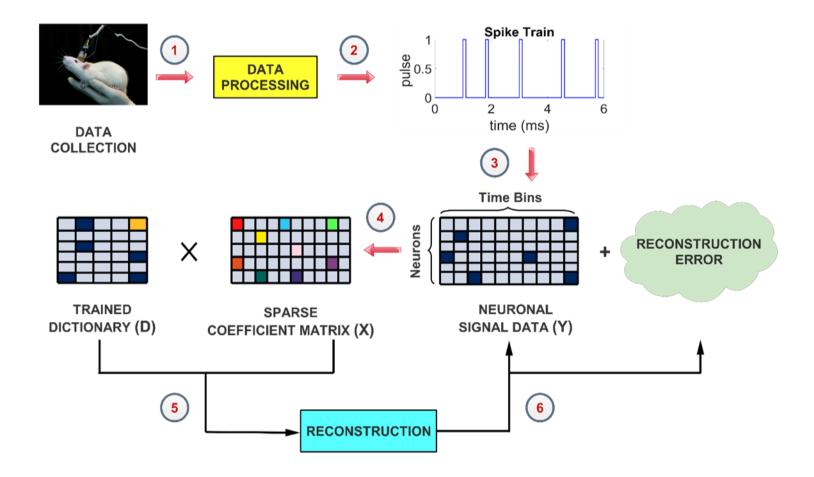
# **Dictionary Update**

For each column k = 1, 2, ..., K in D update it by

- Define the group of examples that use this atom,  $\omega_{\kappa} = \{i | 1 \le i \le N, x_T^k(i) \ne 0\}$
- Compute the overall representation error matrix,  $E_k$ , by  $E_k = Y \sum_{j \neq k} d_j x_T^j$
- Restrict  $E_k$  by choosing only the columns corresponding to  $\omega_{\kappa}$ , and obtain  $E_k^R$ .
- Apply SVD decomposition  $E_k^R = U\Sigma V^T$ . Choose the updated dictionary column  $d'_k$  to be the first column of U.

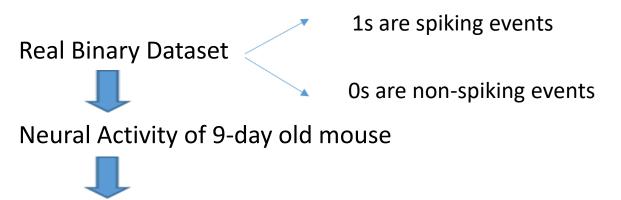


# **Proposed Dictionary Learning Framework**

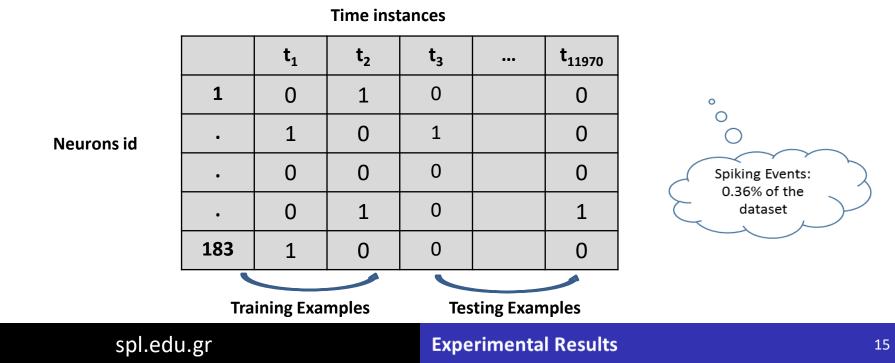


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### Dataset



29 min. spontaneous activity (11970 frames of 0.1451 sec.)



## **K-SVD Performance - Parameters**

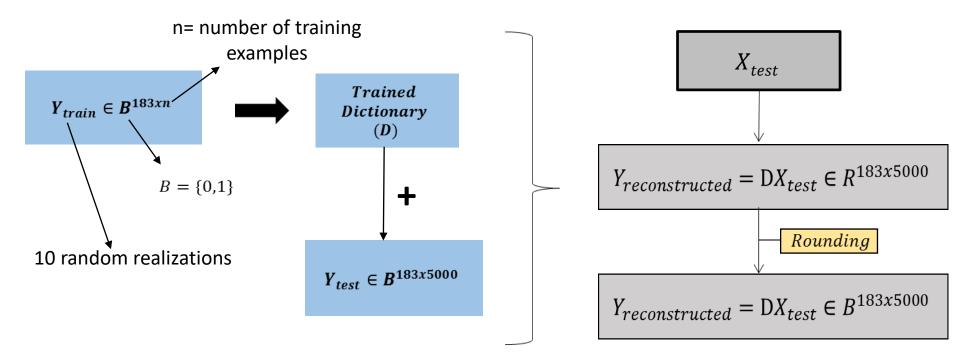
K-SVD Performance in neuronal signal reconstruction in terms of:

- i. Dictionary size
- ii. Sparsity level
- iii. Training size used for dictionary learning

Can we achieve a good reconstruction?

Can we model the data?

# **Experimental Setup**

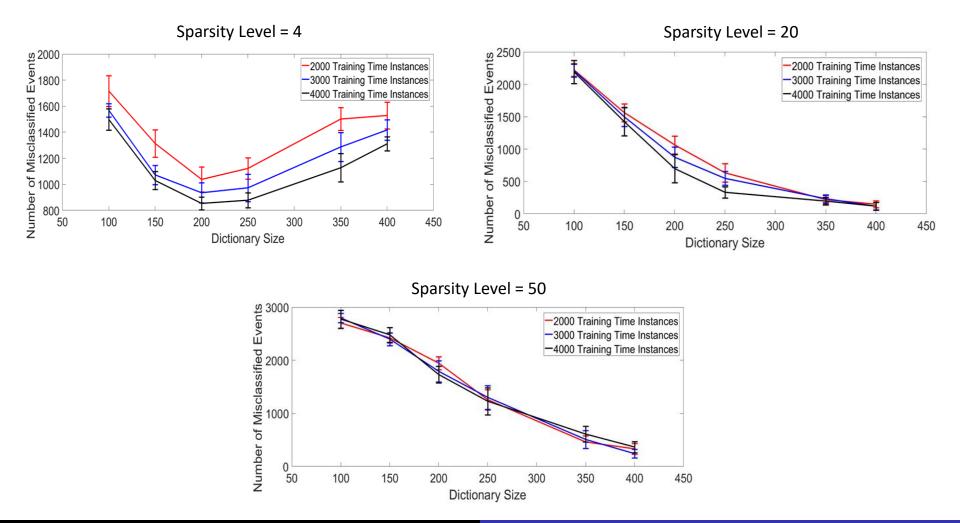


Number of misclassified Events = # { $Y_{test} \neq Y_{reconstructed}$ }

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# **Impact of the Examined Parameters**

Total number of events = 915000 (183x5000)



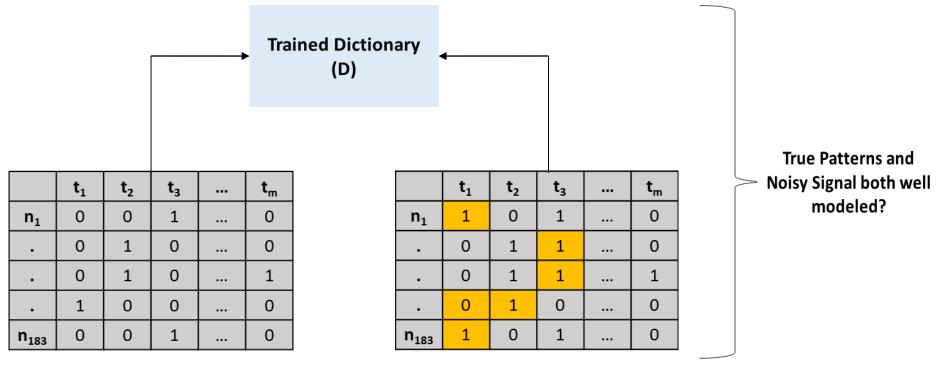
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### **Confusion Matrix of the Reconstructed Events**

Dictionary Size = 400

Training Examples		2000		4000	
Sparsity	Predicted Actual	0	1	0	1
4	0	99.982	0.017	1	0
	1	58.914	41.085	46.636	53.363
20	0	99.997	0.00241	99.998	0.00120
	1	19.668	80.331	18.491	81.508
50	0	99.982	0.017	99.998	0.00186
	1	32.639	67.36	52.82	47.179

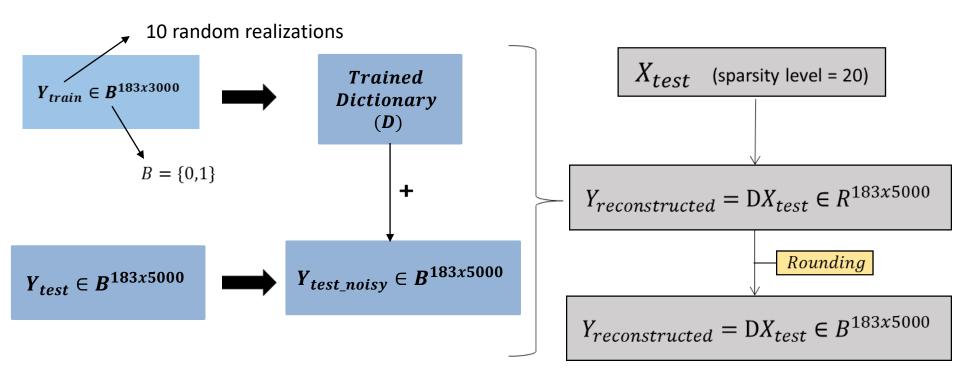
# **Trained Dictionary – Sensitivity to noise**



True Patterns



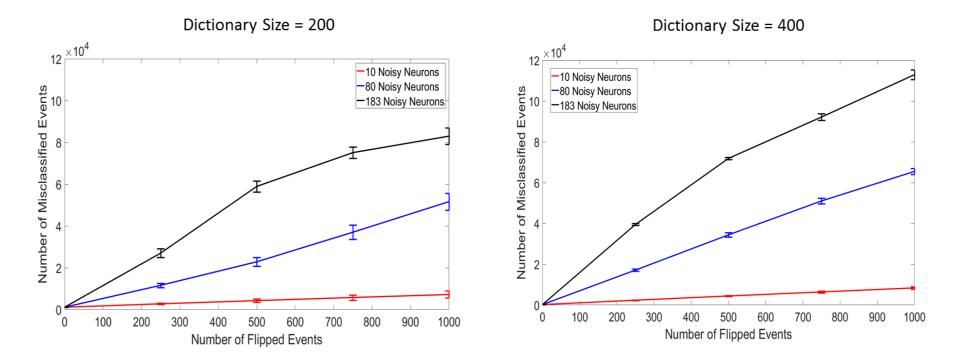
# **Experimental Setup**



Number of misclassified Events =  $\# \{Y_{test\_noisy} \neq Y_{reconstructed}\}$ 

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#### Total number of events = 915000 (183x5000)



Number of misclassified Events =  $\# \{Y_{test\_noisy} \neq Y_{reconstructed}\}$ 

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# **Conclusion – Concerns – Future Work**

### Neuronal Signals – Dictionary Learning

- Effectively represented in low-dimensional subspaces
- > Small training size is adequate
- Average Sparsity level

### Dictionary – Sensitivity to noise

Random noise is not modeled

### Concerns - Future Work

- > Deal with other types of noise (e.g. Circularly Shifted Events)
- Find a suitable metric to check the consistency of the dictionary
- Focus on qualitative characteristics of the Dictionary
- Adversarial Learning Methods

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#### Conclusion



### ACKNOWLEDGMENT

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